

Swiss Confederation





super computing systems

SCS



# Towards a full GPU version of the COSMO model

#### Status of the COSMO priority project Performance on Massively Parallel Architectures (POMPA)

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- COSMO Priority Project POMPA
- Why GPUs are attractive for COSMO
- Approach
- Results
- Outlook
- Conclusion

## **COSMO Priority Project POMPA**



- Performance On Massively Parallel Architectures
- 4 year project (09.2010 09.2014)
- Projects HP2C COSMO & HP2C OPCODE of the initiative HP2C (High Performance & High Productivity Computing) funded by the Swiss Universities embedded
- HP2C finishes mid of 2013
- Goal

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Prepare the COSMO code for these future high performance computing (HPC) architectures







- Massive parallelism increase in number of cores, stagnant or decreasing clock frequency
- Less and "slower" memory per thread memory bandwidth per instruction/second and thread will decrease, more complex memory hierarchies
- Heterogeneous hardware mixed clusters of CPUs and accelerators (GPUs)
- Only slow improvements of inter-processor and inter-thread communication – interconnect bandwidth will improve only slowly
- Stagnant I/O sub-systems technology for long-term data storage will stagnate compared to compute performance

#### We need to adapt our codes in order be efficient in the future!

Towards COSMO on GPUs | COSMO User Seminar 2013 philippe.steiner [at] meteoswiss.ch





Chip CPU (Interlagos)









- Leverage high peak performance of GPU
- CPU and GPU have different memories



- Low FLOPs count per load/store (stencils!)
- Transfer of data on each timestep too expensive





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* - -	Part	Time/∆t	VS	§ Transfer of ten prognostic variables 118 ms
	Dynamics	172 ms		
	Physics	36 ms		
	Total	253 ms		

## All code which touches the prognostic variables within timestep has to be ported





Common goal of the projects HP2C COSMO / HP2C OPCODE

**GPU-implementation of "full" timestep of COSMO** 

Aim for...

- Completeness (i.e. full COSMO model)
- Performance (i.e. lower time-to-solution)
- Portability / Maintainability (i.e. no hacks)
- Durability (i.e. knowledge transfer and documentation)

#### •Time/resource constraints lead to compromises







#### **Dynamical core**

- Small group of developers
- Memory bandwidth bound
- Complex stencils (3D)
- 60% of runtime

#### → Complete rewrite in C++/CUDA

- $\rightarrow$  Development of a stencil library
- → Development of new communication library (GCL)
- → Target architecture CPU (x86) and GPU.
- $\rightarrow$  Extendable to other architectures
- $\rightarrow$  Long term adaptation of the model

#### **Physics and Data Assimilation**

- Large group of developers
- Code may be shared with other models
- Less memory bandwidth bound
- Large part of code (50% of the lines)
- 20% of runtime
- → GPU port with compiler directives (OpenACC)
- $\rightarrow$  Little code optimization
- → Some parts stay on CPU
- → Most ported routines currently have CPU and GPU version

## **Operation of Dynamical Core**



#### Test domain 128x128x60. CPU: 16 cores Interlagos; GPU: Tesla X2090

#### **CPU Version**

•Factor 1.6x – 1.8x faster than the COSMO dycore

•No explicit use of vector instructions (potential for 10-30% improvement)

#### **GPU Version**

•Same generation GPU is roughly a factor 2.6x faster than CPU

•Potential for further performance optimizations



#### Speedup (lower limit)

## Performance of Physics



• Test domain 128x128x60 – 16 cores CPU vs GPU (Kepler)



- Overall speed up ~4x
- Similar performance with OpenACC (Cray and PGI compiler)
- Running the GPU-Optimized code on CPU is about 25% slower

 $\rightarrow$  separate source code for time critical routines



## **Current Status**



Setup

4	🔶 Input	→ keep on CPU / copy to GPU			
	Physics	→ directives, (soil, radiation, microphysics, turbulence)			
	Dynamics	→ C++/CUDA rewrite, (RK dynamical core)			
Λt					
<b></b>	Assimilation	→ directives, (nudging)			
	Halo-update	→ communication library (GCL), (halo, scatter/gather)			
	Diagnostics	→ directives, only bare essentials			
	Output	→ keep on CPU / copy from GPU			
	Cleanup				



## **Ongoing tasks**



- Porting of dynamical core
  - lateral boundary relaxation (Carlos Osuna, C2SM)
  - new fast waves solver (Michael Baldauf, DWD)
  - explicit horizontal diffusion (Master student, ETH)
  - semi-Lagrangian advection (Bachelor student, ETH)
- Porting of physical parametrizations
  - Tiedtke convection scheme (Cristiano Padrin, CINECA)
  - Graupel microphysics (Bachelor student, ETH)
- Inter-GPU communication in Fortran code
- Integration and testing of GPU version



## **Demonstrator (HP2C OPCODE)**



 Prototype implementation of the COSMO production suite of MeteoSwiss making aggressive use of GPU technology



 Same time-to-solution on substantially cheaper hardware: Factor ~3x in price, factor ~9x in power consumption Reduction in infrastructure costs







- Complete rewrite of dynamical core using stencil library
  - Single source code for GPU and CPU
  - Modern software engineering
  - Speedup of 2x for CPU and 5x for GPU
- Porting of rest of code using compiler directives
  - Physics (Speedup 4x for GPU)
  - Assimilation (no speedup)
- Demonstrator by June 2013!
- Completion and integration of these developments into COSMO code until 2014





### Thank you for your attention





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Domain decomposition with 1 CPU core and 1 GPU per subdomain

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Multicore CPU







## **Dycore: Sandy Bridge vs. Kepler**

