

# Assimilating 3D radar reflectivity with an Ensemble Kalman Filter on a convection-permitting scale

## COSMO User Seminar 2015

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*Special thanks to U. Blahak (DWD), H. Reich (DWD), C. Schraff (DWD), Y. Zeng (LMU)*

March 03, 2015

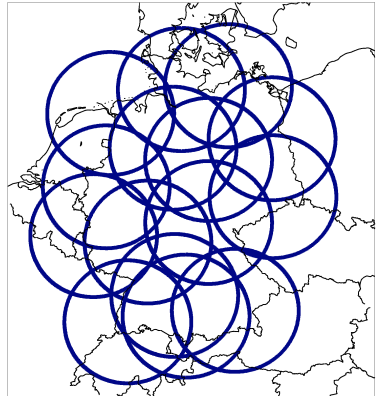
# Motivation

## Goal

- ▶ Improve short-term model forecasts of convective events

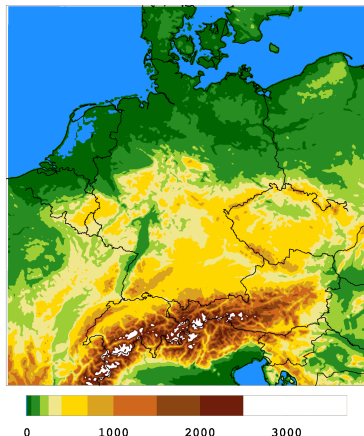
## Radar data

- ▶ High resolution in both space + time, dense coverage
- ▶ 3D information
- ▶ Here: only radar reflectivity.  
Radial winds: Y. Zeng (LMU),  
M. Würsch (LMU) → poster



## COSMO-DE and LETKF

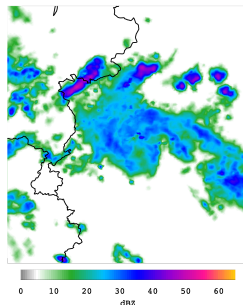
- ▶ **KENDA:** Local Ensemble Transform Kalman Filter (**LETKF**) for COSMO-DE (developed at DWD, following Hunt et al., 2007)
- ▶ Propagate non-linear model equations
- ▶ Estimate flow-dependent covariances
- ▶ 40 ensemble members + 1 deterministic run



## Radar forward operator

**Simulate synthetic 3D radar scan based on COSMO-DE model fields (EMRADSCOPE, developed at DWD/KIT)**

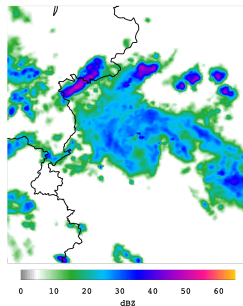
- ▶ **No-reflectivity:** set all values below 5 dBZ to 5 dBZ
- ▶ **Superobbing:** achieve relatively homogeneous horizontal data distribution
  - Reduce computational costs
  - Relax necessity of direct match between model and obs (double penalty problem)



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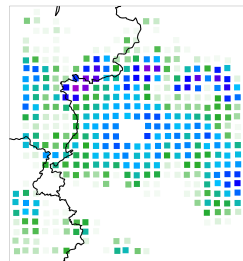
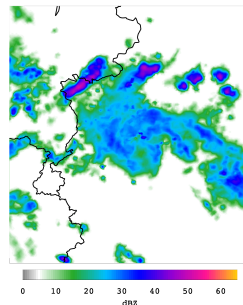
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## Cycling study

### Case study: May 26th 2014

- ▶ Spinup from 0-12 UTC (no data assimilation)
- ▶ 3h cycling (12-15 UTC) followed by 6h free forecast (15-21 UTC)

#### CONV

Assimilated obs:  
conventional (synop, temp,  
airep)

#### RADAR+CONV

Assimilated obs:  
reflectivity, no-reflectivity,  
conventional

- ▶ Study influence of update frequencies: **5, 15, 30, 60 minutes**
- ▶ Consider all available data since last analysis

## Det run 15min update: Analysis cycle (Reflectivity)

**Observation:**

**CONV:**

**RAD+CONV:**



## Det run 15min update: Forecast window (Reflectivity)

**Observation:**

**CONV:**

**RAD+CONV:**

## **FG ensemble 15min update: Analysis cycle** **(#ens members > 20dBZ)**

**Obs (> 20dBZ):**

**CONV:**

**RAD+CONV:**

## **FG ensemble 15min update: Forecast window (#ens members > 20dBZ)**

**Obs (> 20dBZ):**

**CONV:**

**RAD+CONV:**

## First verification

### In observation space: Fraction Skill Score

- ▶ compares model and observation based on exceedance of a dBZ threshold
- ▶ ranges from 0 to 1, perfect score 1

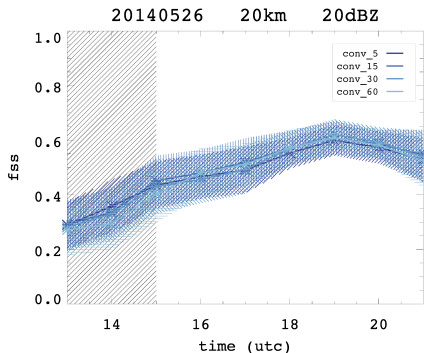
### In model space:

#### Equitable Threat Score, Frequency Bias

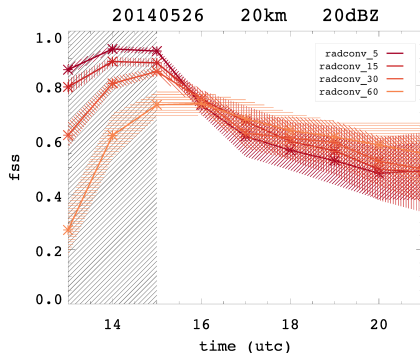
- ▶ compares precipitation rate from the model against radar derived precipitation rate (mm/h)
- ▶ ETS ranges from  $-1/3$  to 1, perfect score 1
- ▶ FBI ranges from 0 to  $\infty$ , perfect score 1

# Fraction Skill Score

**CONV:**

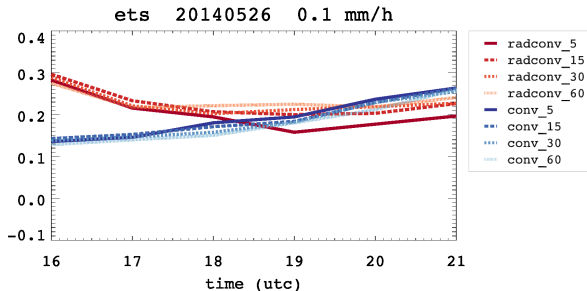


**RADAR+CONV:**

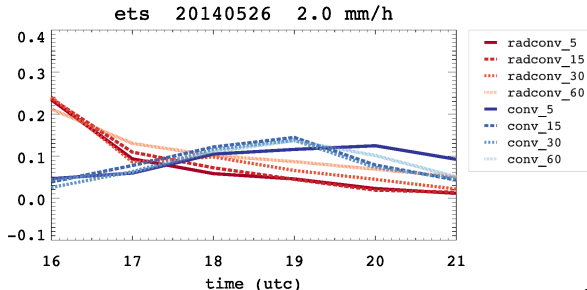


# Equitable threat score

**0.1 mm/h:**



**2.0 mm/h:**

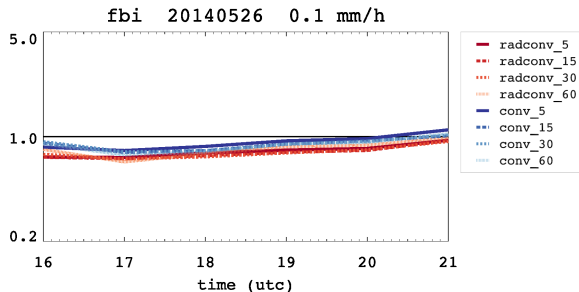


(Forecast initialized at 15 UTC)

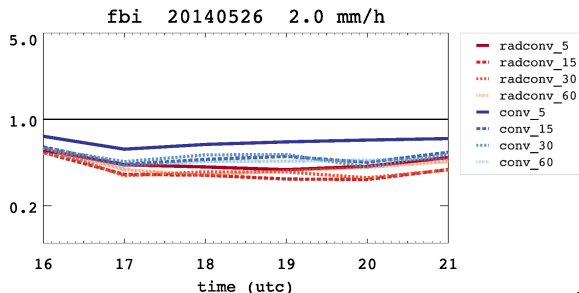


# Frequency bias

**0.1 mm/h:**



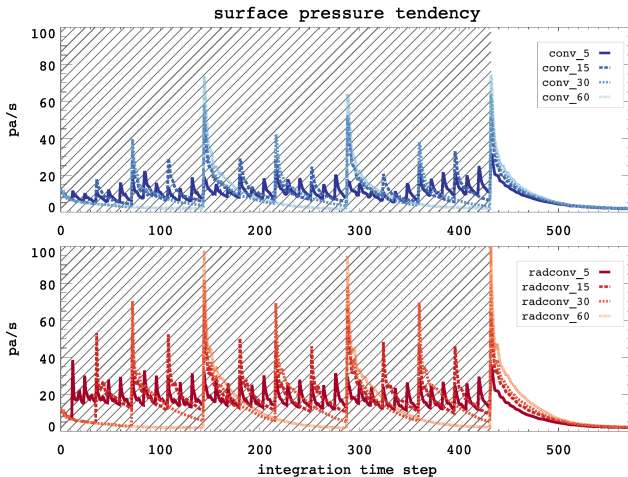
**2.0 mm/h:**



(Forecast initialized at 15 UTC)

# Surface pressure tendency during assimilation

A measure of noise in a model:





## Summary: Radar reflectivity assimilation in KENDA

- ▶ So far we investigated only 1 case study
- ▶ In terms of FSS, assimilating radar reflectivity yields very good agreement between analysis and observation
- ▶ Forecast impact is visible during first 2-4 hours in both FSS and ETS
- ▶ Underestimation of precipitation intensity in all experiments
- ▶ Less precipitation in RADAR experiment - different treatment of no-rain obs necessary?
  
- ▶ After 1h forecast, 60 min update seems superior to 5 min update
- ▶ Rapid updates do not allow the model to adjust from changes introduced by data assimilation

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